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4 8 Full file at <https://testbanku.eu/Solution-Manual-for-Control-Systems-Engineering-7th-Edition-by-Nise> 1-14 Chapter 1: Introduction The characteristic polynomial is  $M^2 + 4(M + 2i)(M - 2i)$  Thus, the total solution is  $x(t) = A \cos(2t) + B \sin(2t) + t^2 + 1 + 4 + 8 + 1 + 9$  Solving for the arbitrary constants,  $x(0) = A - = 1$  Therefore,  $A = .$

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